

The DF-150 is a member of the DF series of Electric Encoders™, based on Netzer precision proprietary technology. The Electric Encoder™ offers many advantages - some unparalleled

- Low profile (13 mm)
- Hollow, floating shaft
- No bearings or other contacting elements
- High resolution and precision
- High tolerance to temperature extremes, shock, moisture, EMI, RFI and Magnetic fields
- Low weight
- Holistic signal generation
- Digital interfaces

The Electric Encoder™ is unique in being holistic, i.e., its output reading is the averaged outcome of the whole area of the rotor, This feature makes the Electric Encoder™ forgiving to mounting tolerances, mechanical wander etc.

The absence of components such as ball bearings , flexible couplers, glass disc, light sources and detectors, along with very low power consumption makes the Electric Encoder™ virtually failure free.

The internally shielded, DC operated Electric Encoder™ includes an electric field generator, a field receiver, a sinusoidal shaped dielectric rotor, and processing electronics.

The output signals of Electric Encoder™ are analog Sine / Cosine representing the rotation angle. The digital outputs are obtained by further processing - which may be either internal or external to the encoder.

The combination of precision, low profile, low weight and high reliability have made Netzer Precision encoders particularly suitable to a wide variety of critical applications including, but not limited to medical equipment and aerospace.



### General

Angular resolution	18-20 bit
Maximum tested static error	±0.010°
Extended accuracy static error	±0.006°
Maximum operational speed	1,500 rpm
Measurement range	Unlimited rotation
Rotation direction	Adjustable CW/CCW*
Build In Test BIT	Optional

\* Default same direction from bottom side of the encoder

### Mechanical

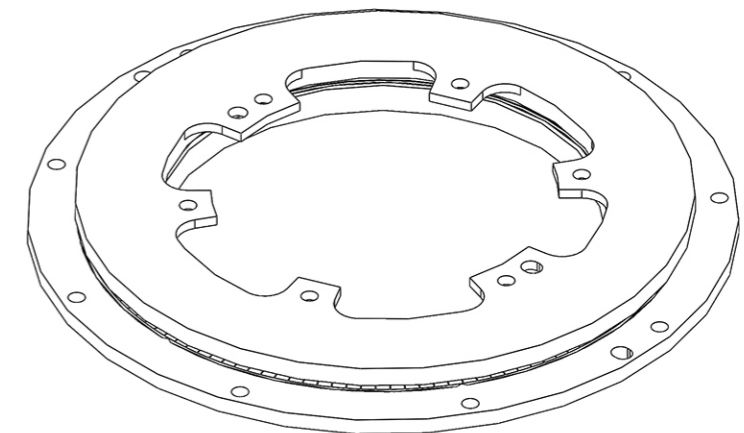
Allowable mounting eccentricity	±0.1 mm
Allowable axial mounting tolerance	±0.1 mm
Rotor inertia	427,882 gr · mm <sup>2</sup>
Total weight	307 gr
Outer Ø /Inner Ø/ Height	150/ 110 / 13 mm
Material (stator, rotor)	Aluminum
Nominal air gap (stator, rotor)	0.6 mm

### Electrical

Supply voltage	5V ± 5%
Interconnection	Shielded cable
Cable length	1,500 mm MAX

### Environmental

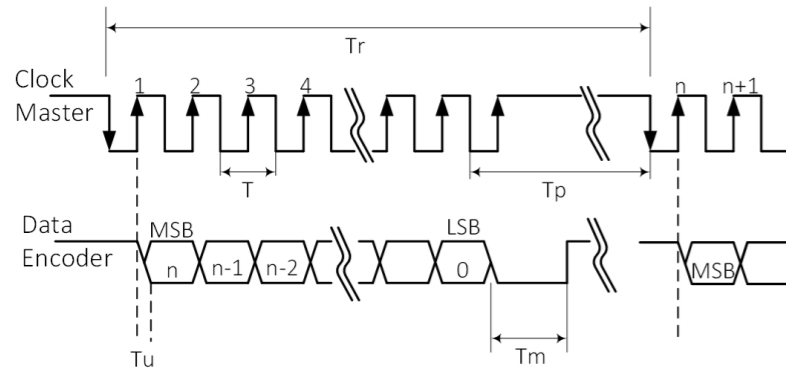
EMC	IEC 6100-6-2, IEC 6100-6-4
Operating temperature range	-40°C to +85°C
Storage temperature	-50°C to +100°C
Relative humidity	98% Non condensing
Shock endurance	100 g for 11 ms
Vibration endurance	20 g 10 – 2000 Hz
Protection	IP 40





### Digital SSI Interface

Synchronous Serial Interface (SSI) is a point to point serial interface standard between a master (e.g. controller) and a slave (e.g. sensor) for digital data transmission.



	Description	Recommendations
n	Total number of data bits	12 - 22
T	Clock period	
f= 1/T	Clock frequency	0.5 - 2.0 MHz
Tu	Bit update time	200 nsec
Tp	Pause time	26 - ∞ µsec
Tm	Monoflop time	>25 µsec
Tr	Time between 2 adjacent requests	Tr > n*T+26 µsec
fr=1/Tr	Data request frequency	

### SSI / BiSS Output signal parameters

Output code	Binary
Serial output	Differential RS-422
Clock	Differential RS-422
Clock frequency	0.5 ÷ 2.0 MHz
Position update rate (Max)	30 kHz
Current consumption	180 mA

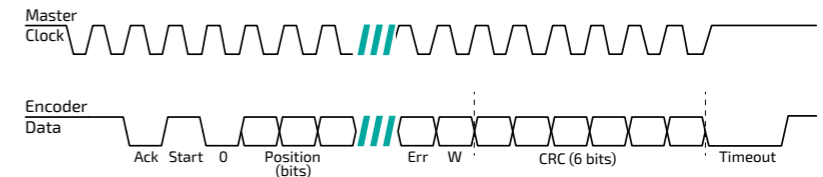
### SSI / BiSS interface wires color code

Clock +	Grey	Clock
Clock -	Blue	
Data -	Yellow	Data
Data +	Green	
GND	Black	Ground
+5V	Red	Power supply



### Digital BiSS-C Interface

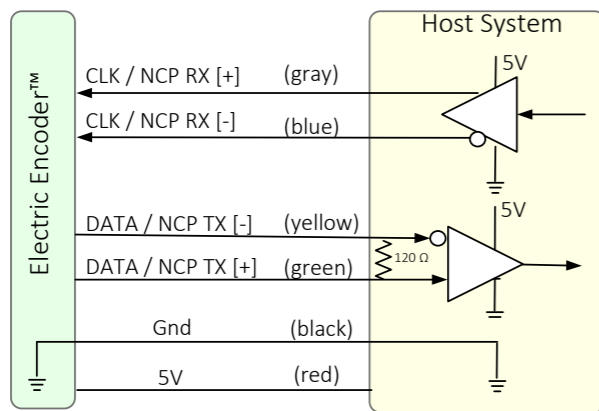
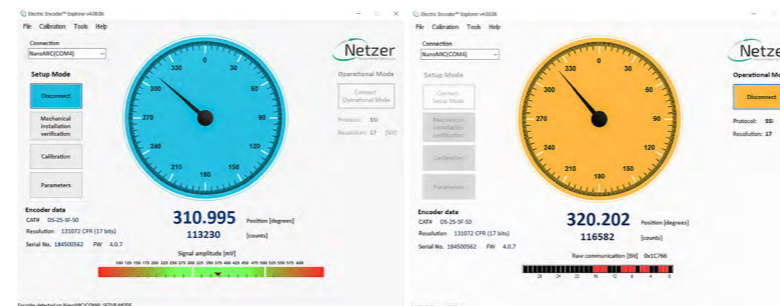
BiSS – C Interface is unidirectional serial synchronous protocol for digital data transmission where the Encoder acts as “slave” transmits data according to “Master” clock. The BiSS protocol is designed in B mode and C mode (continuous mode). The BiSS-C interface as the SSI is based on RS-422 standards.



bit #		Description	Default	Length
28	Ack	Period during which the encoder calculates the absolute position, one clock cycle	0	1/clock
27	Start	Encoder signal for “start” data transmit	1	1 bit
26	“0”	“start” bit follower	0	1 bit
8...25	AP	Absolute Position encoder data		
7	Warn.	Warning	1	1 bit
6	Error	Error	1	1 bit
0...5	CRC	The CRC polynomial for position, error and warning data is: $x^6 + x^1 + x^0$ . It is transmitted MSB first and inverted. The start bit and “0” bit are omitted from the CRC calculation.		6 bits
	Timeout	Elapse between the sequential “start” request cycle’s.		25 µs

### Software tools: (SSI / BiSS - C)

Advanced calibration and monitoring options are available by using the factory supplied [Electric Encoder Explorer software](#). This facilitates proper mechanical mounting, offsets calibration and advanced signal monitoring.



### Ordering Code

DF - 150 - 32 - S G - S 0 - n n n

DF Product line

Outer Diameter

Fine ECR

Output

S	SSi
I	BiSS

Resolution

Code	Bit	CPR
G	18	262,144

BIT (Build In Test): optional

[ ]	None
B	BIT

EA Extended Accuracy

nnn Custom

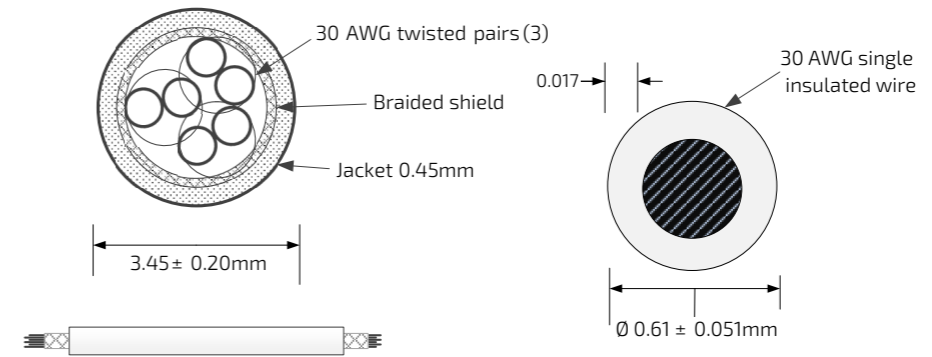
Interconnection

0	250mm Flying leads (default)
1	500mm Flying leads (default)
2	750mm Flying leads (default)
3	1000mm Flying leads (default)
C	Connector (optional)
S	Shielded cable 250 mm (default)

### Cable Information

Cable: 30 AWG twisted pair(3):2 (30 AWG 25/44 finned copper, 0.15 PFE to  $\varnothing 0.6 \pm 0.05$  OD).  
Temperature rating: -60 to +150 Deg C.  
Braided shield: Thinned copper braided 95% min. coverage.  
Jacket: 0.45 silicon rubber jacket  $\varnothing 3.45 \pm 0.2$  OD

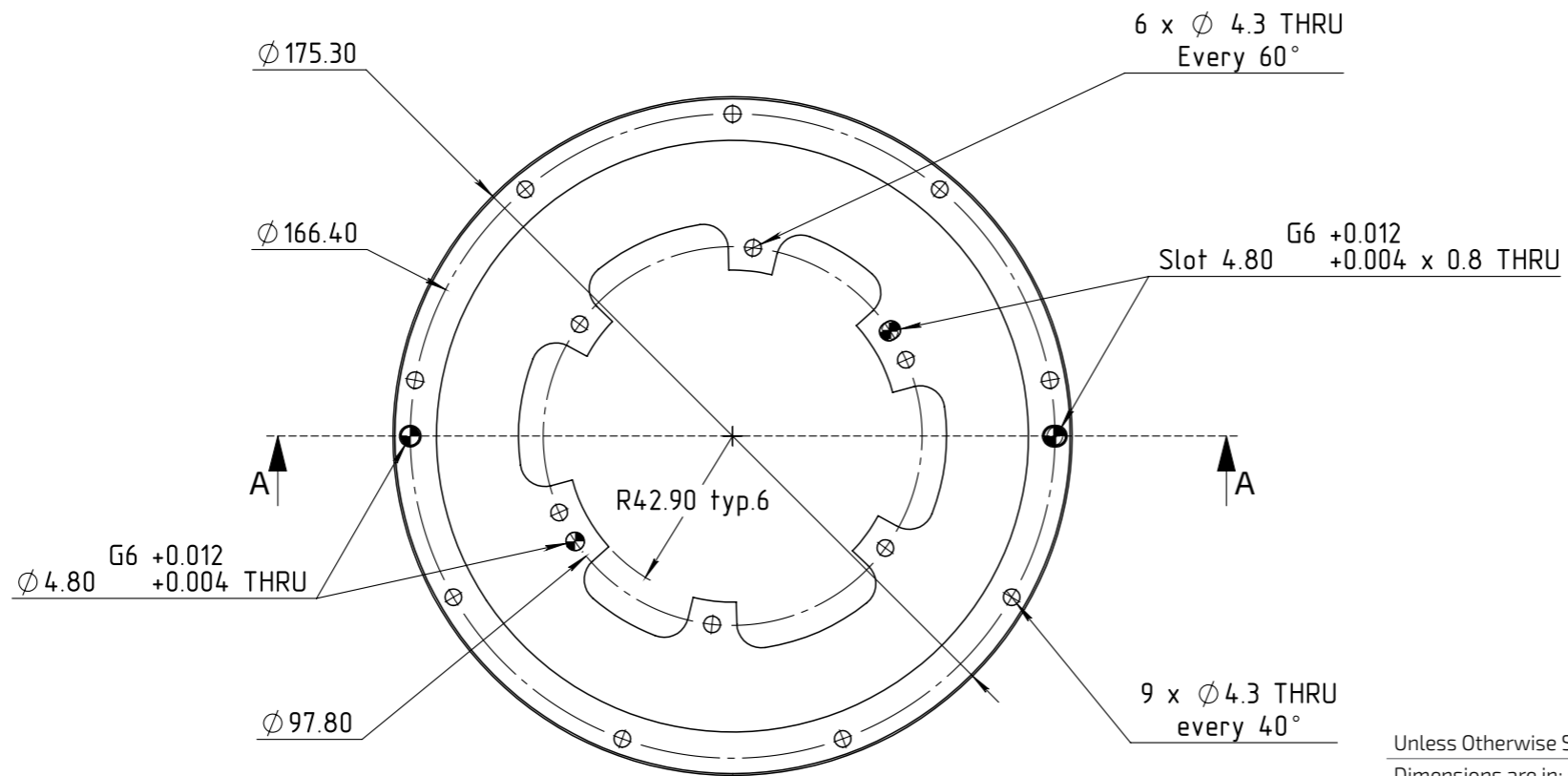
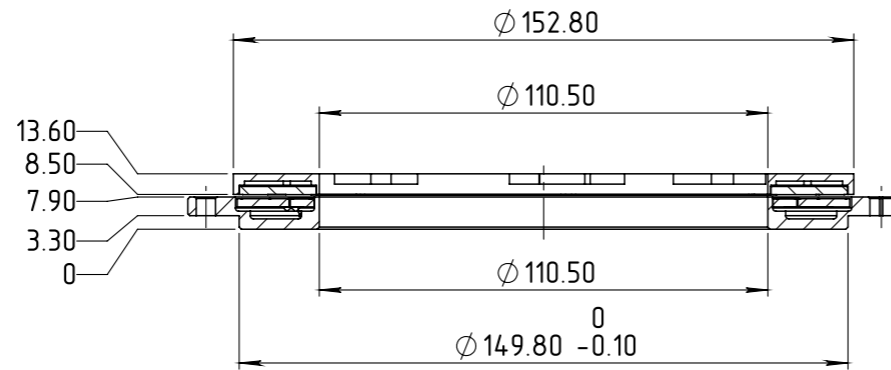
Pair#	Color
1	Red / Black
2	Gray / Blue
3	Green / Yellow



### Related documents

DF-150 User Manual: Mechanical, Electrical and calibration setup.

**SECTION A-A**



Unless Otherwise Specified

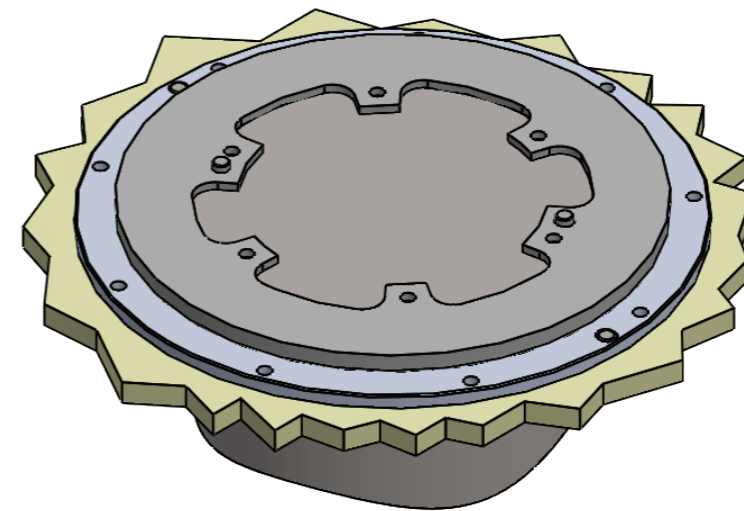
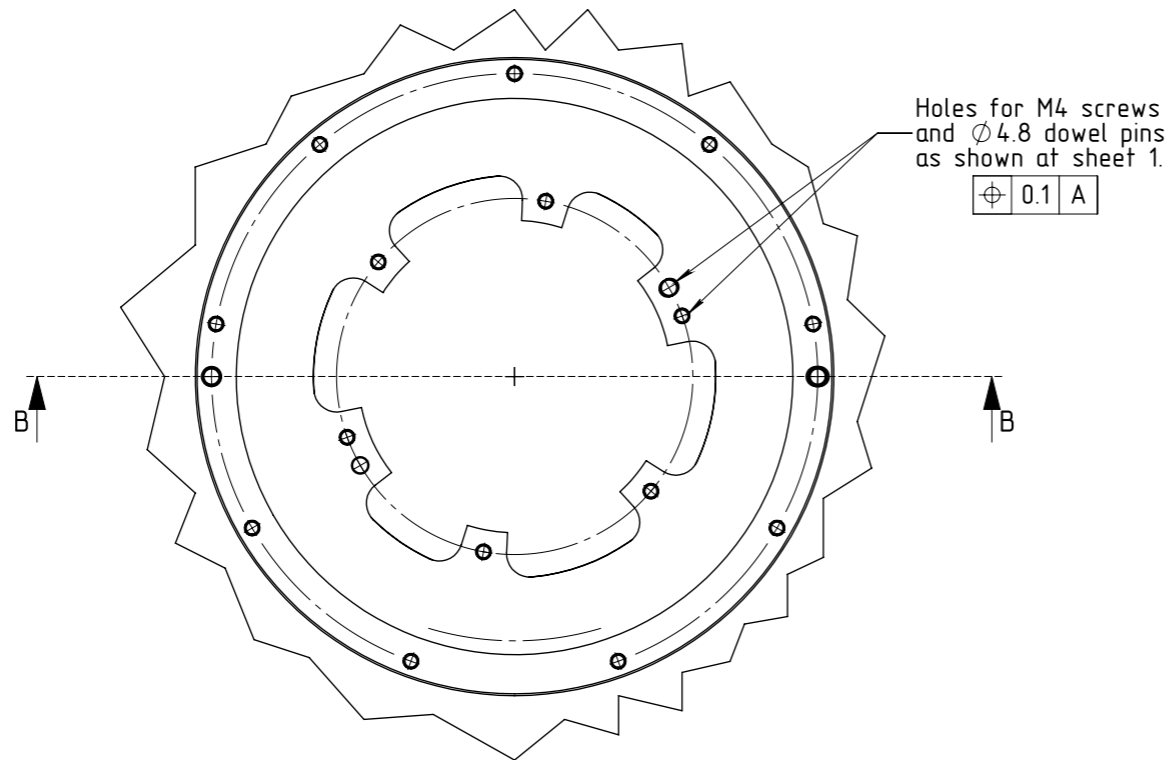
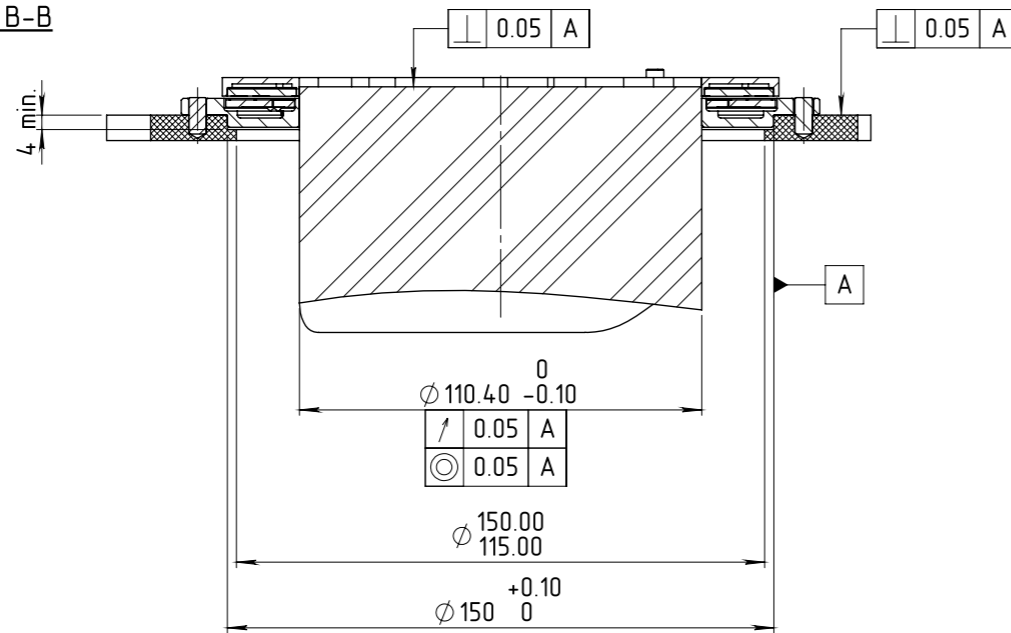
Dimensions are in: mm | Surface finish: N6

Linear tolerances

0.5-4.9:  $\pm 0.05$  mm | 5-30:  $\pm 0.1$  mm

31-120:  $\pm 0.15$  mm | 121-400:  $\pm 0.2$  mm

**SECTION B-B**



Unless Otherwise Specified

Dimensions are in: mm | Surface finish: N6

Linear tolerances

0.5-4.9:  $\pm 0.05$  mm | 5-30:  $\pm 0.1$  mm

31-120:  $\pm 0.15$  mm | 121-400:  $\pm 0.2$  mm